Report on Summer Student Program JINR-2015 (students.jinr.ru) summer program:

Configuration of cluster environment from scratch with IPMI, ZFS and InfiniBand

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About this document

This report intends to allow reproduction of performed work, analysis and expansion of provided results.

Task

Configuration of a SuperBlade system installed in a rack (an analog to Hybrilit[1] cluster) from scratch: from bios+raid setup to InfiniBand (IB) application selection and performance tuning and analysis. Use of Scientific Linux 6.6 OS is a must.

Setup

Given a SuperBlade server with two diskless systems (blade nodes) installed in a rack that looks like this:

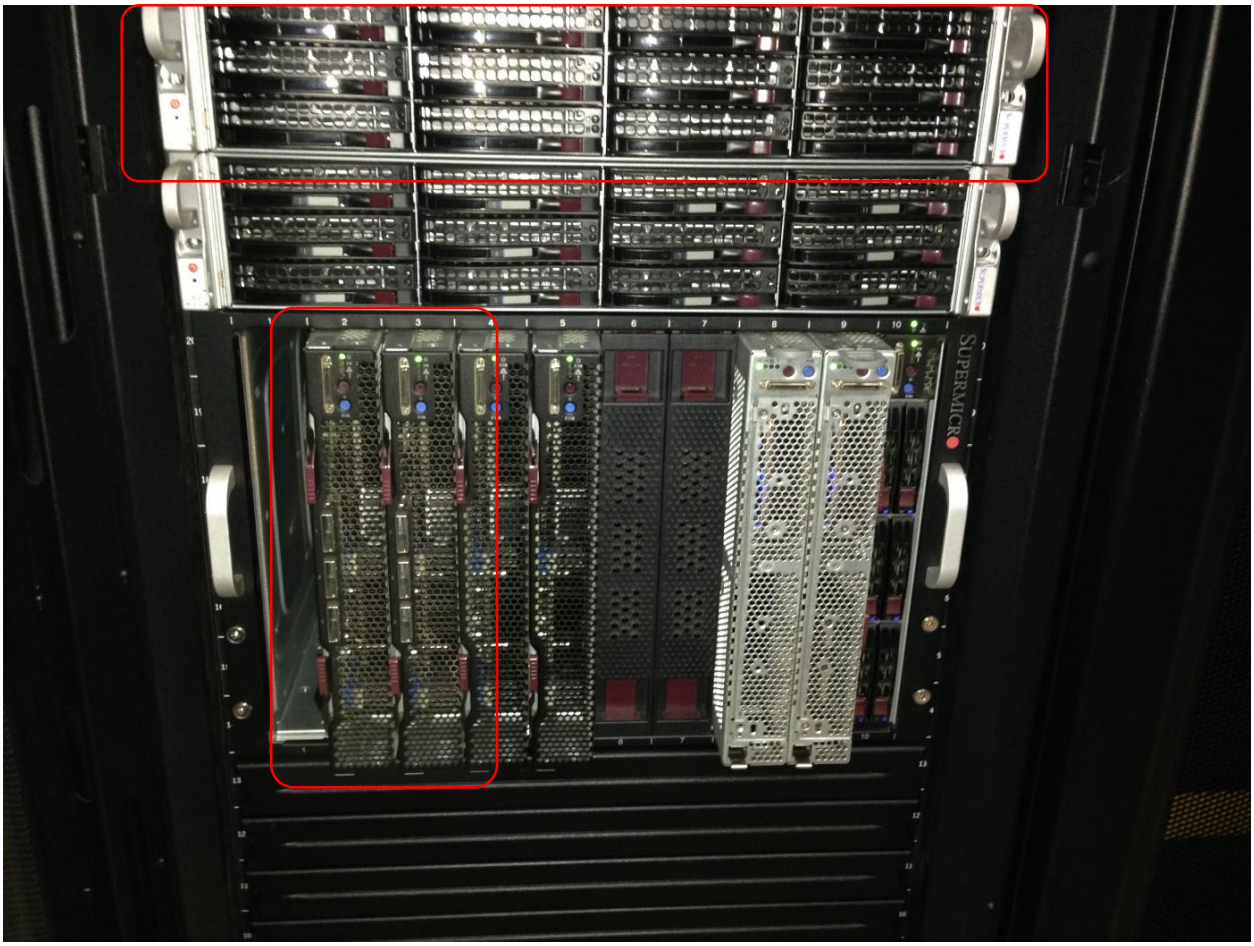

Figure 1: part of Hybrilit cluster, parts provided for experimentation selected in red. A server node and two blades.

Access

Server and blade were available via IPMI. After installation of Operating System (OS) access should be performed over SSH.

[1] http://hybrilit.jinr.ru/

LiveCD SMB/Windows Share hosting

IPMI allows remote .iso file mounting for OS installation onto Server. It supports Server Message Block (SMB) (aka Windows Share) protocol. To host SMB server with Scientific Linux 6.6 .iso LIT JINR cloud infrastructure[2] was used.

A *openvz_scientific_6-x86_64_krb_clst33* VM was allocated. Special dedicated user was created for files ownership. We installed and configured *samba* server to share user folder.

Samba configuration

A few lines were changed in samba configuration (`/etc/samba/smb.conf`) `[global]` group:

```
workgroup = WORKGROUP
wins support = yes
encrypt passwords = true
```

Then folder was shared:

```
[share]
path = /home/observer/share
available = yes
read only = yes
browsable = yes
public = yes
guest ok = yes
create mask = 0755
```

Samba Server was restarted

```
sudo service smb restart
```

Local SMB testing

An sl66.iso LiveCD file was placed into `/home/observer/share` folder, rights to folder and its contents were passed to the user.

```
[root@cldvm131 ~]#  smbclient //159.93.33.131/share apmath@JINR -U observer
Domain=[WORKGROUP] OS=[Unix] Server=[Samba 3.6.23-14.el6_6]
smb: \> ls
  .                                   D        0  Thu Aug 13 15:25:56 2015
  ..                                  D        0  Fri Aug  7 18:57:16 2015
  sl66.iso                            731906048  Wed Nov 12 21:40:03 2014
  hello                                       4  Fri Aug  7 19:26:44 2015
  sl66dvd.iso                         2733637632  Wed Nov 12 21:40:48 2014

                41115 blocks of size 262144. 7325 blocks available
smb: \> _
```

Figure 2: SMB samba server was tested locally using smbclient.

VM configuration

Ports required to share data over SMB were opened.

```
-A INPUT -s 77.51.0.0/16 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
-A INPUT -s 188.184.0.0/16 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
-A INPUT -s 137.138.0.0/16 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
-A INPUT -s 95.221.0.0/16 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
```

[2] https://cloud.jinr.ru/

```
-A INPUT -s 91.203.80.0/22 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
-A INPUT -s 62.84.96.0/19 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT
-A INPUT -s 159.93.0.0/16 -p tcp -m state --state NEW -m tcp --dport 455 -j ACCEPT

-A INPUT -s 77.51.0.0/16 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 188.184.0.0/16 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 137.138.0.0/16 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 95.221.0.0/16 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 91.203.80.0/22 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 62.84.96.0/19 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
-A INPUT -s 159.93.0.0/16 -p tcp -m state --state NEW -m tcp --dport 139 -j ACCEPT
```

Lines were appended to `/etc/sysconfig/iptables`, and

```
service iptables restart
```

was performed.

Global SMB testing

Samba was tested from remote Windows PC:

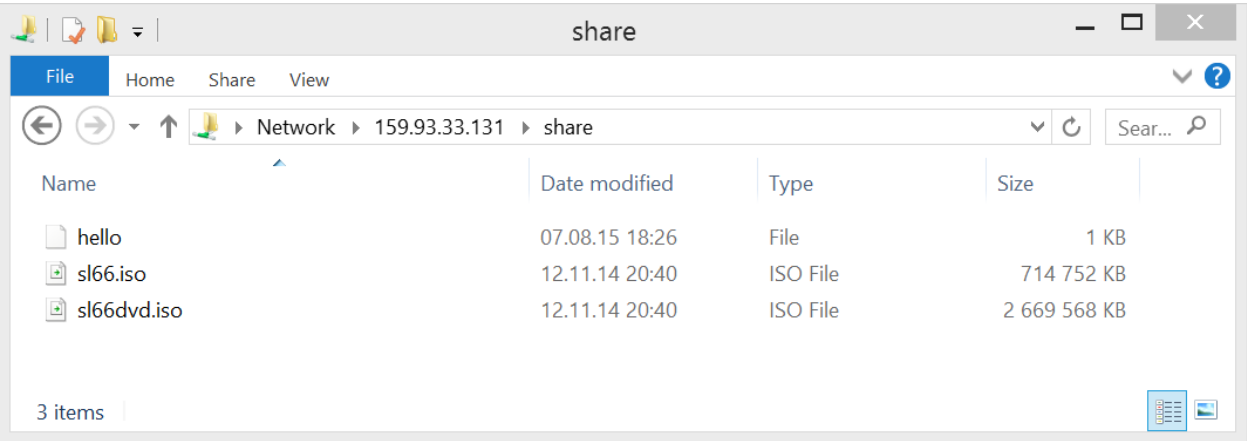

Figure 3: Windows Explorer showing remote directory.

And from another cloud VM:

```
[root@cldvm132 ~]#  smbclient //159.93.33.131/share/ apmath@JINR -U observer
Domain=[WORKGROUP] OS=[Unix] Server=[Samba 3.6.23-14.el6_6]
smb: \> ls
  .                                   D        0  Thu Aug 13 15:25:56 2015
  ..                                  D        0  Fri Aug  7 18:57:16 2015
  sl66.iso                            7  731906048  Wed Nov 12 21:40:03 2014
  hello                               7        4  Fri Aug  7 19:26:44 2015
  sl66dvd.iso                         7 2733637632  Wed Nov 12 21:40:48 2014

                41115 blocks of size 262144. 7325 blocks available
```

Figure 4: SMB client showing remote directory.

Now OS installation could be performed over IPMI.

Path to Mac -> Windows 8-> SMCIPMITool configuration

There are 3 ways to use IPMI: Web UI, GUI Client (IPMIView), Command Line Interface (SMCIPMITool).

To interact with server Supermicro provides IPMI iKVM Java viewer. It requires to use native libraries on that are provided for Windows and Linux.

So having a Mac Book workstation we had to install VM with Windows or Linux on top of it. Windows 8.1 was selected for ease of use.

IPMI Web Site Viewing

In hopes for remote work capabilities tunneling was studied. A cloud VM was used to tunnel connection. It allowed us to view website from any location. However we found out, underlying iKVM native libraries use UDP ports so one cannot use simple TCP tunnels.

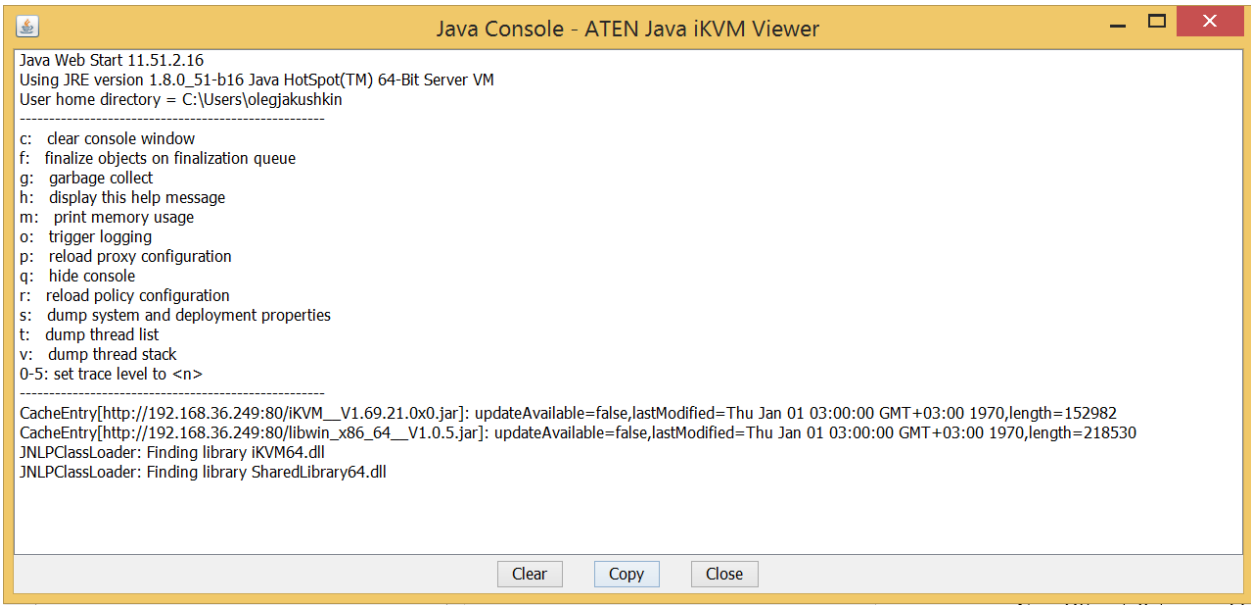

Figure 5: iKVM connection error.

Web UI was effective to get a fast look at current overall server state. Its iKVM viewer is only updated with hos IPMI and has shown bugs like black not rendered parts of screen in latest Java 8 version.

Virtual media hosting was also unclear and could not mount our SMB stored iso file.

IPMIView

Same thing was with IPMIView iKVM interface – parts of it were rendered as black. Virtual Media facileties were acting unclearly.

SMCIPMITool

Shown to be best in iKVM rendering performance and provided clear manual on details such as virtual media use.

We started it with

```
# SMCIPMITool.exe 192.168.36.249 oleg password shell
```

And then it was used as interactive shell.

To mount and unmount an iso we used `vmwa` commands:

```
vmwa dev2iso \\159.93.33.131\share\sl66.iso
vmwa dev2stop
```

To start iKVM we used

```
kvmwa
```

command.

SMCIPMITool errors

In case of *vmwa exception*:

```
java.lang.NullPointerException
        at com.supermicro.ipmi.UDPSocket.sendPacket(UDPSocket.java:213)
        at com.supermicro.ipmi.RMCP.send(RMCP.java:155)
        at
com.supermicro.ipmi.IPMIMessagingCommand.GetSystemGUIDCommand(IPMIMessagingCommand.java:70)
        at com.supermicro.ipmi.IPMIMessagingCommand.getSystemGUID(IPMIMessagingCommand.java:891)
        at
com.supermicro.ipmi.IPMIMessagingCommand.getSystemGUIDByIP(IPMIMessagingCommand.java:918)
        at com.supermicro.ipmi.text.ShellCommand.getPrompt(ShellCommand.java:425)
        at com.supermicro.ipmi.text.ShellCommand.execute(ShellCommand.java:274)
        at com.supermicro.ipmi.text.SuperBladeTool.execute(SuperBladeTool.java:2186)
        at com.supermicro.ipmi.text.SuperBladeTool.main(SuperBladeTool.java:2127)
        at sun.reflect.NativeMethodAccessorImpl.invoke0(Native Method)
        at sun.reflect.NativeMethodAccessorImpl.invoke(NativeMethodAccessorImpl.java:39)
        at sun.reflect.DelegatingMethodAccessorImpl.invoke(DelegatingMethodAccessorImpl.java:25)
        at java.lang.reflect.Method.invoke(Method.java:597)
        at com.zerog.lax.LAX.launch(DashoA10*..)
        at com.zerog.lax.LAX.main(DashoA10*..)
```

That kills *SMCIPMITool* process just call

```
ipmi reset
```

This will warmly restart IPMI and cure UDP socket error.

Server node

Server BIOS setup

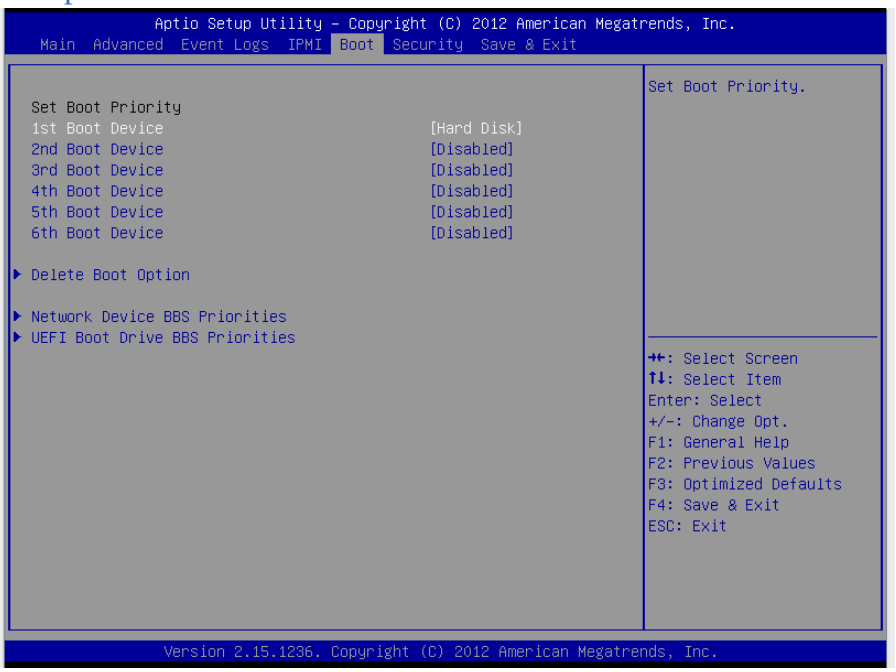

Figure 6: BIOS before IPMI boot device selection

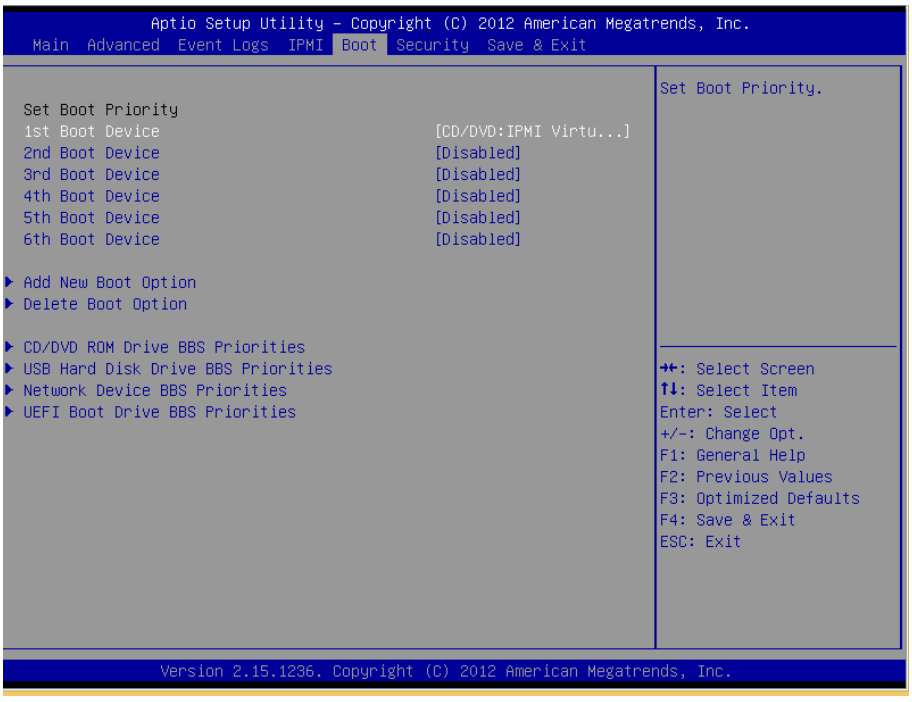

Figure 7: BIOS after IPMI boot device selection

Server Hardware RAID setup

We need to setup RAID, a ZFS one, yet hard drives shall be available for partitioning on the OS side. Thus we need to show hard drives to OS while hard drives shall not be inside RAID array.

Most described way of doing such RAID controller configuration is using WebBios. There are even video tutorials for Supermicro motherboards[3].

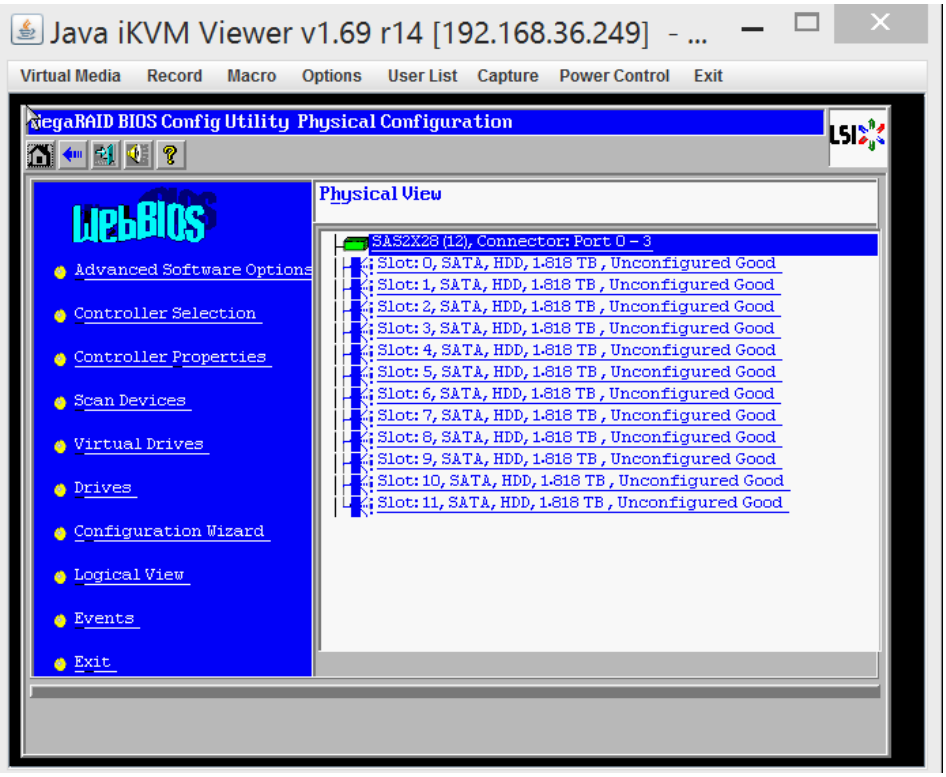

Figure 8: WebBIOS RAID setup with mouse locked on top right corner.

WebBios only supports PS/2 mouse. IPMI provides only USB mouse emulation over iKVM. Thus mouse will always stay in the top left corner. So we can not setup RAID from WebBios over IPMI. Lets look at alternatives!

We could try to access it over LiveCD! After installing a LiveCD of Scientific Linux 6.6 we found out it has no internet connection… We tried to configure it but on Scientific Linux `gedit`, `vi` and others crush out of the box with I/O and segmentation errors respectively not being able to start network file creation. And GParted cannot see anything obviously.

[3] https://www.youtube.com/watch?v=woo_3PywYE0

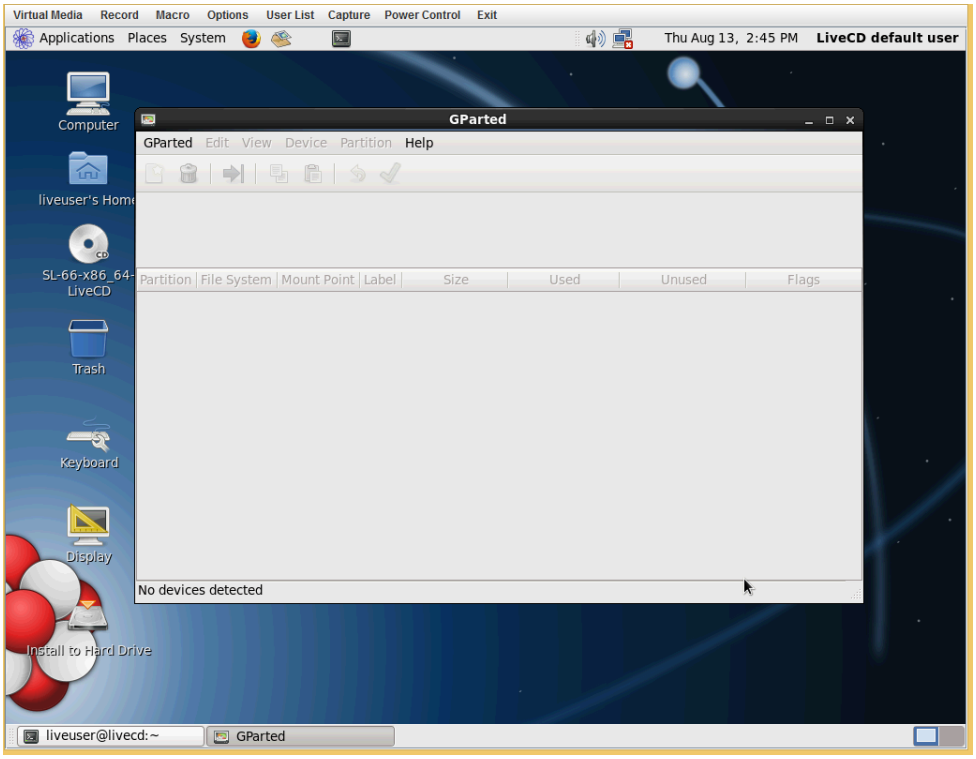

Figure 9: LiveCD GParted can not see hard drives.

So our last resort will be a Preboot CLI " **MegaPCLI SAS RAID Management Tool**" over IPMI iKVM. Tool cannot scroll its output and nearly always output is larger than screen size thus iKVM video recorder is helping us to inspect what happened on command call. Also Preboot CLS is not a Linux thus traditional information pipelining and filtering will not work.

So first call would be `-h -aALL` that would print out a lot of information that is correlating with many other **MegaCLI** documents. For more introductory information on MegaCLI, MegaPCLI and its differences (Chapter 5) inspect Offical Manual[4] and numerous blog posts like this one[5]. Note that sometimes we also used WebBIOS video tutorial for reference on how to read this help for example to correlate help line:

```
-CfgLDAdd -RX[E0:S0,E1:S1,...] [WT | WB] [NORA | RA] [Direct |
Cached] [CachedBadBBU|NoCachedBadBBU] [-szXXX [-szYYY ...]] [-strpszM]
[-Hsp[E0:S0,...]] [-AfterLdX] | -Force [FDE|CtrlBased] [-Cache] [-enblPI
-val] -aN
```

With its meaning

Now lets get information on enclosures: `-EncInfo -aALL`

[4] http://www.cisco.com/c/dam/en/us/td/docs/unified_computing/ucs/3rd-party/lsi/mrsas/userguide/LSI_MR_SAS_SW_UG.pdf
[5] http://artipc10.vub.ac.be/wordpress/2011/09/12/megacli-useful-commands/

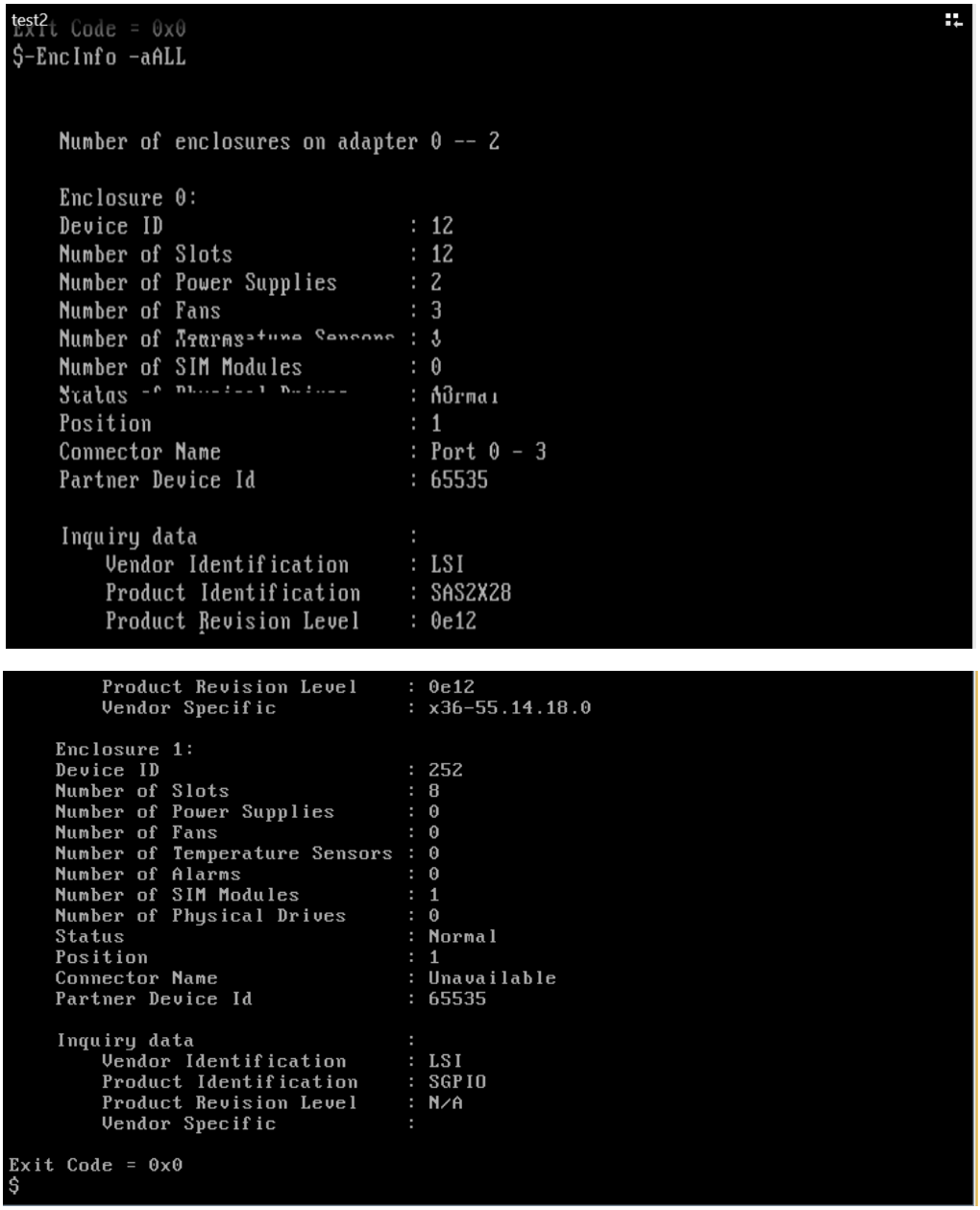

Figure 10: MegaPCLI help recovered from video.

We can now get info on individual discs using `PDInfo -PhysDrv [12:1] -aALL` where 12 means device id and 1 is a slot number (we have 12 slots, numbering starts from 0).

For ZFS we want to get 12 virtual drive groups with 1 hard drive per group.

Following this manuals on this topic from University of California[6], Davis and University of Cambridge[7] we export all MegaRAID drives for Linux Software RAID

```
-CfgEachDskRaid0 WB adra cached -a0
```

[6] http://www.maths.cam.ac.uk/computing/docs/public/megacli_raid_lsi.html
[7] https://wiki.cse.ucdavis.edu/support:general:megacli

And get nice view in GParted when LiveCD is installed

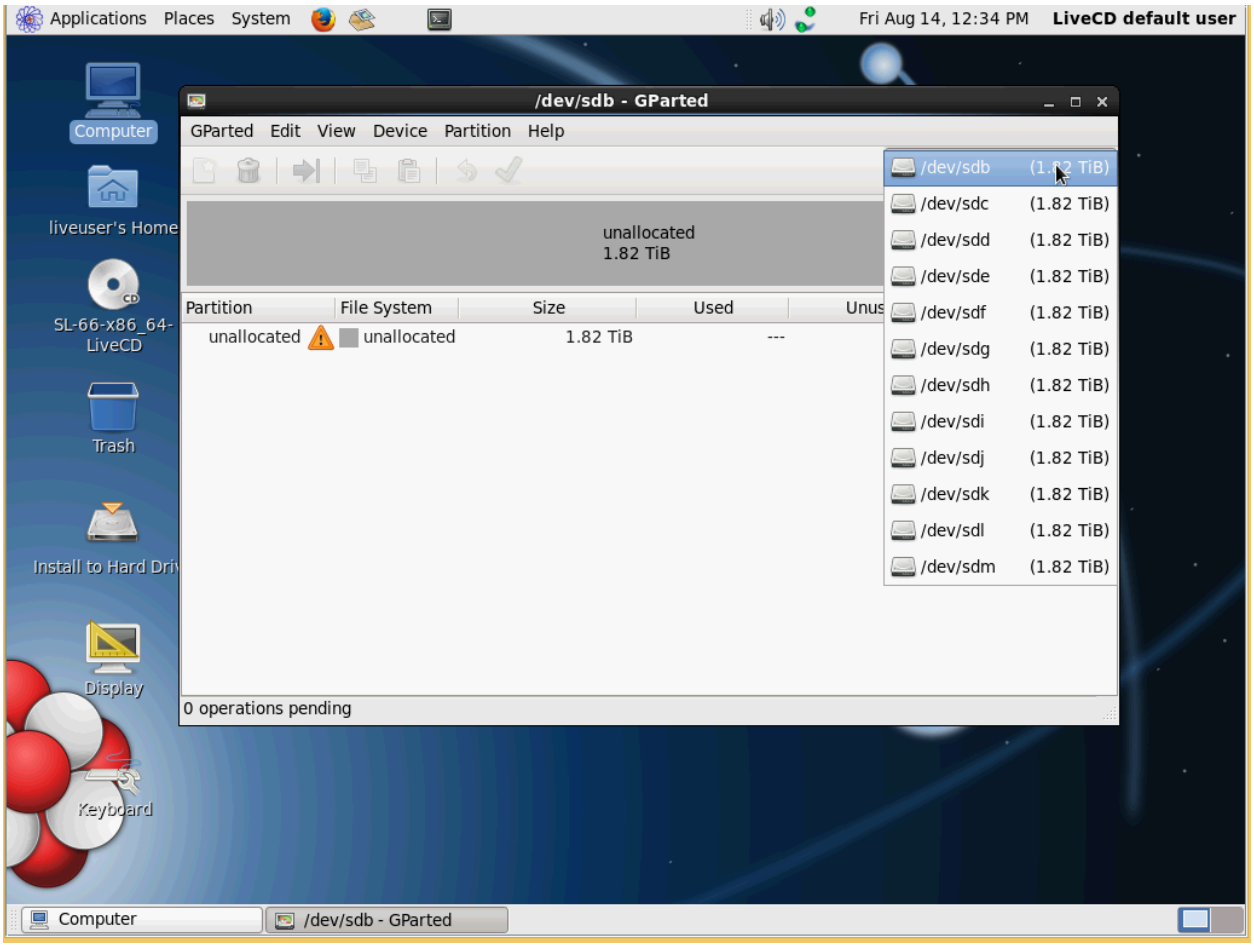

Figure 11: LiveCD GParted view after MegaPCLI call.

OS Installation

When we can see hard drives from LiveCD live gets much simpler! We will be mainly following this[8] blog post for OS installation and ZFS configuration.

Let's call Install to Hard drive icon on LiveCD desktop.

We will be installing on one hard drive

[8] https://rudd-o.com/linux-and-free-software/installing-fedora-on-top-of-zfs

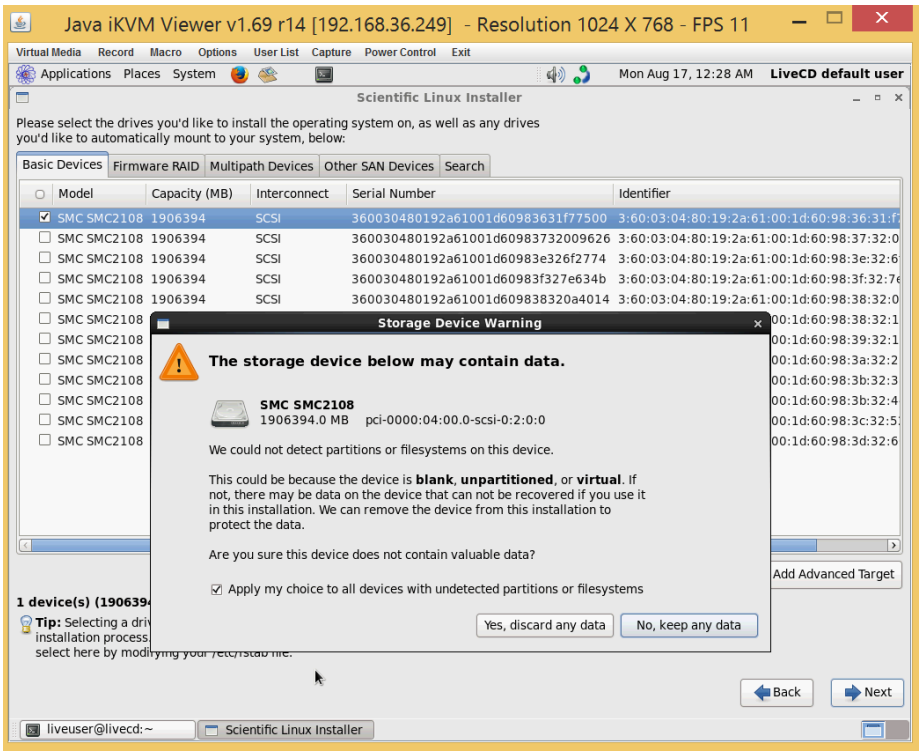

Figure 12: LiveCD Installation step.

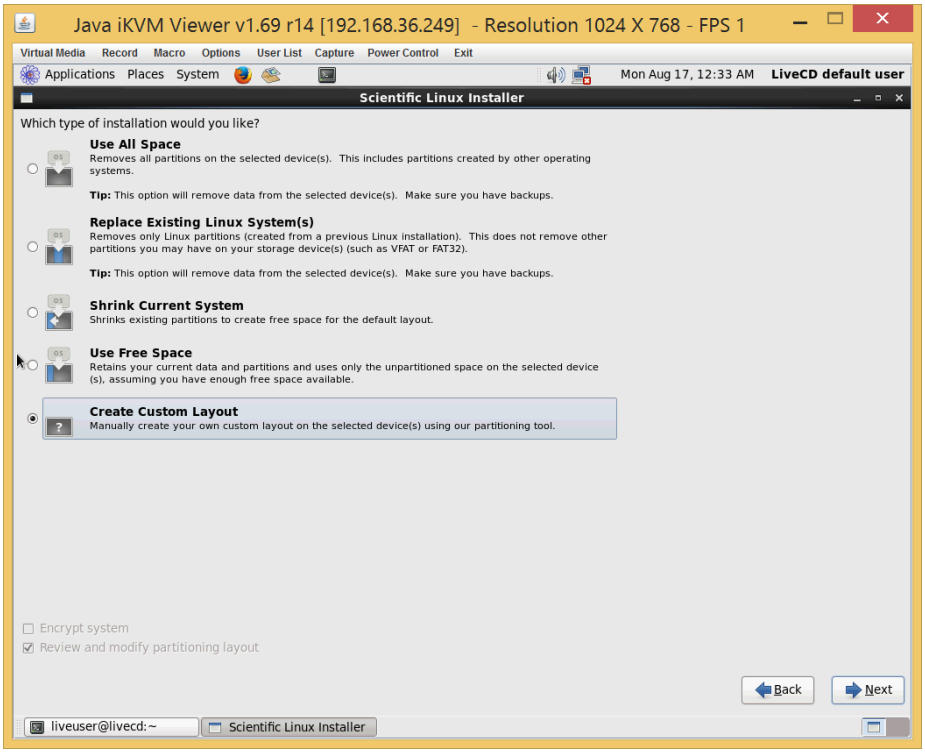

Figure 13: LiveCD Installation step.

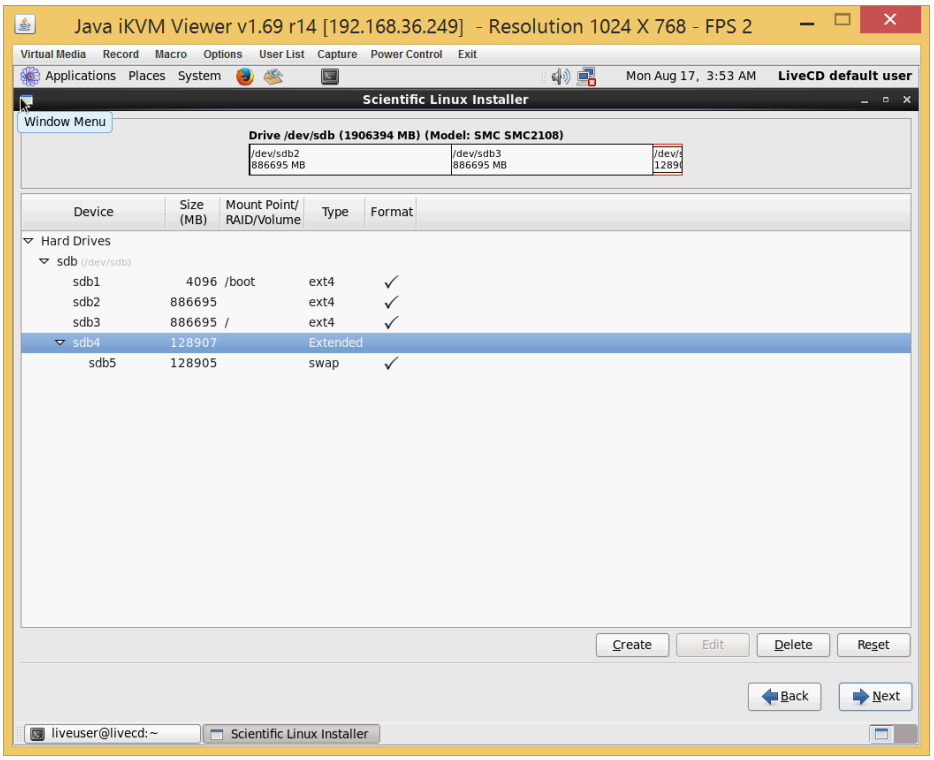

Figure 14: LiveCD Installation step.

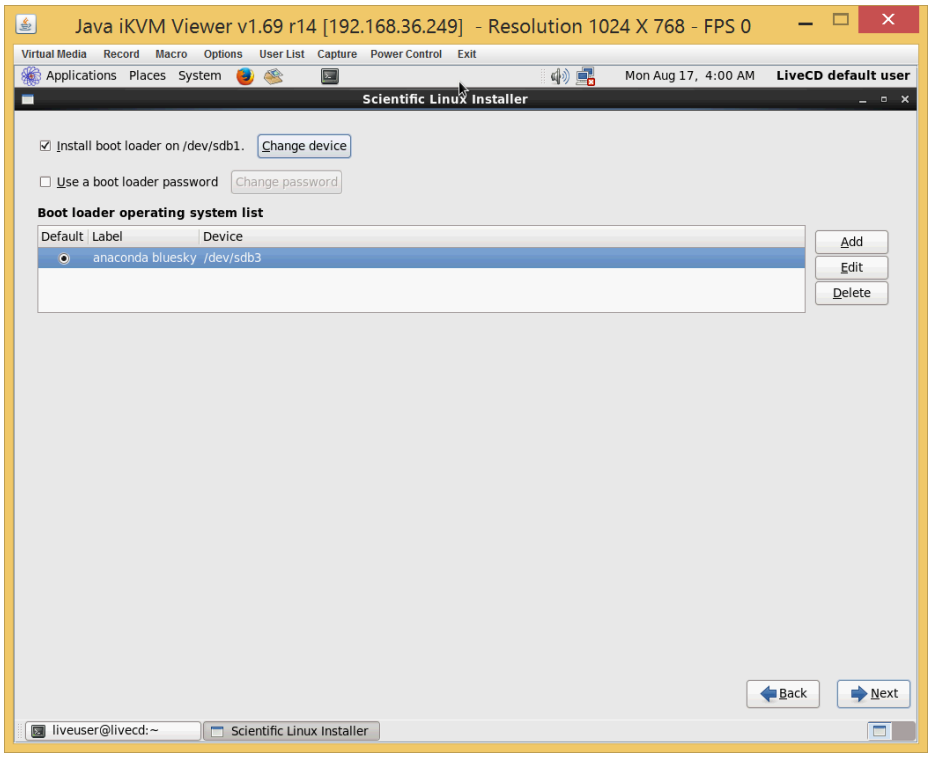

Figure 15: LiveCD Installation step.

After LiveCD finishes installation, we stop virtual media device and perform power reset.

LiveCD Errors

Mainly errors occur when IPMI virtual media that mounts LiveCD Drive over SMB lost connection. Errors may include failed application launch, system initialization fails.

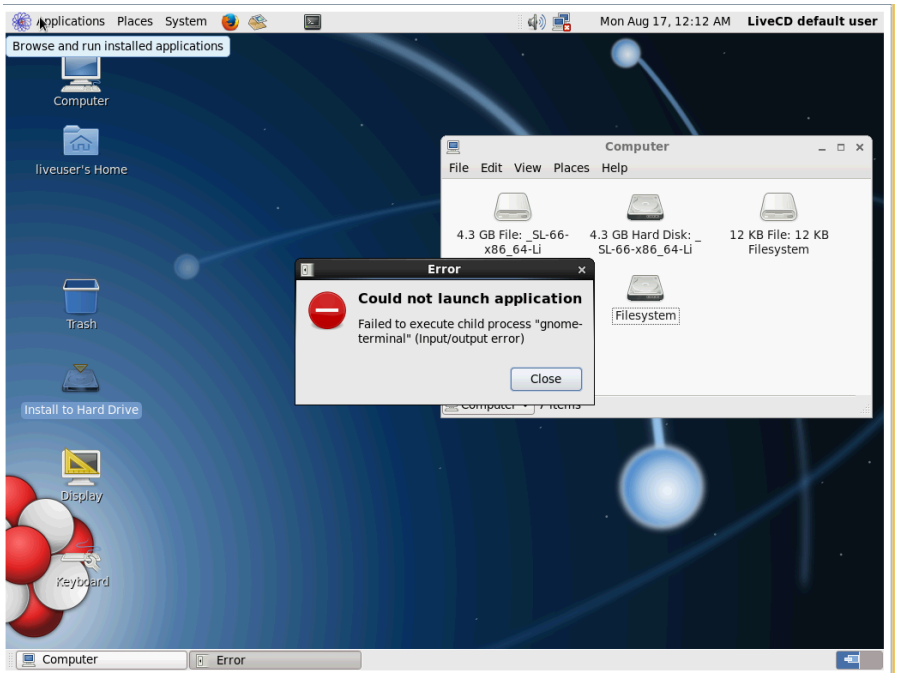

Figure 16:Errors due to IPMI Virtual Media connection loss

In such cases virtual media device stop+start+Pover Reset helps

```
vmwa dev2stop
vmwa dev2iso \\159.93.33.131\share\sl66.iso
Power Reset button on iKVM top menu bar
```

Then we open BIOS and select another boot device

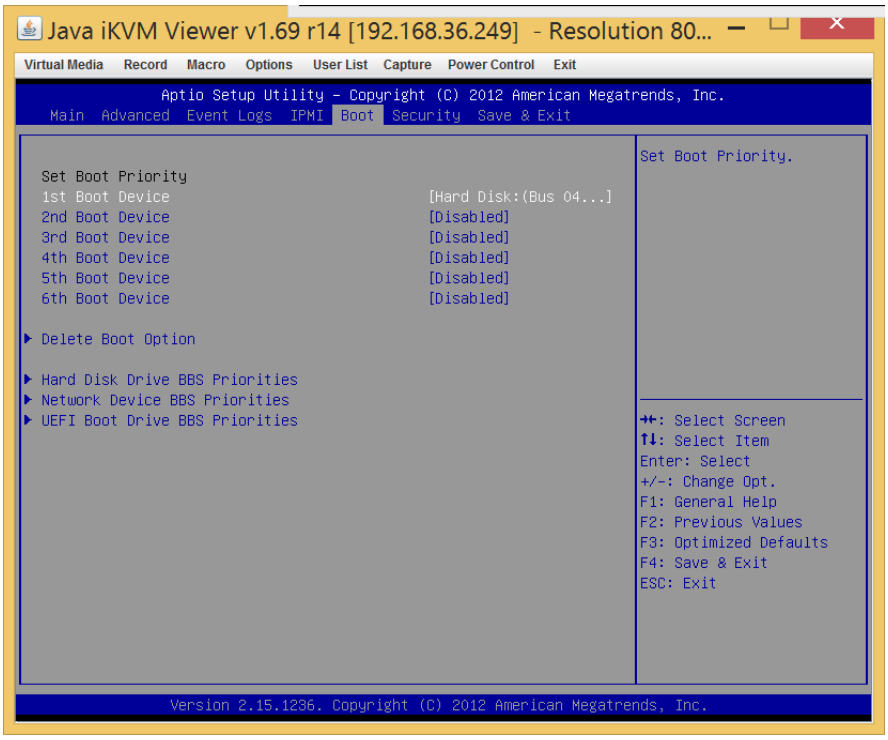

Figure 17:New boot device is selected.

We do not see out drive partitions here – only hard drive system abstraction, select it, save and reboot.

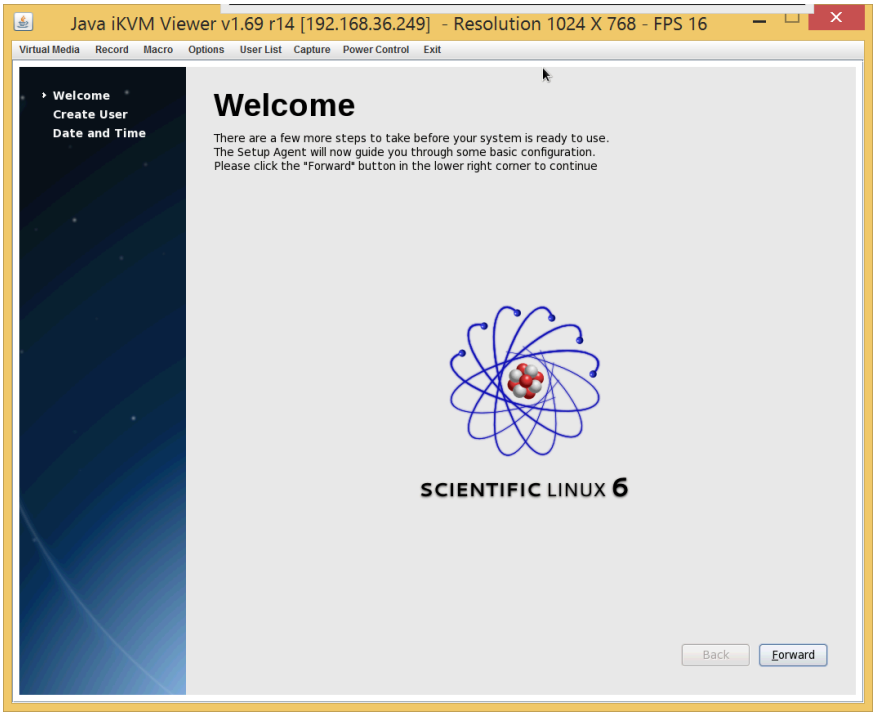

Figure 18: Scientific Linux welcome screen.

System will load.

Set up the network and SSH

Lets login as superuser

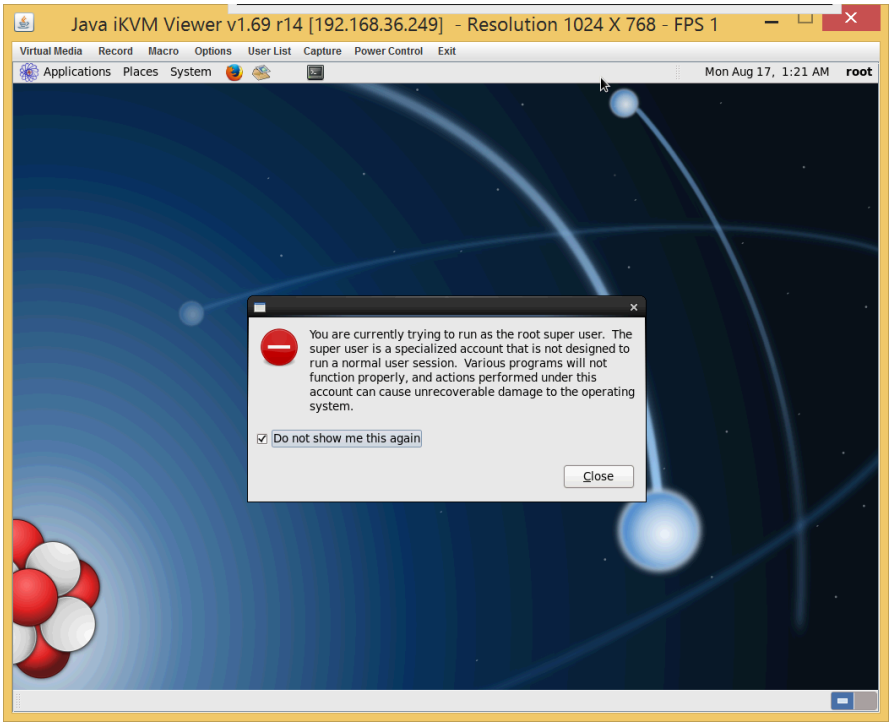

Figure 19: We logged into root on installed system.

We create *ifcfg-eth0*

```
gedit /etc/sysconfig/network-scripts/ifcfg-eth0
```

and fill it with public network settings

```
DEVICE="eth0"
BOOTPROTO="static"
BROADCAST="159.93.36.255"
DNS1="159.93.14.7"
DNS2="159.93.17.7"
GATEWAY="159.93.36.1"
IPADDR="159.93.36.249"
NETMASK="255.255.255.0"
NM_CONTROLLED="yes"
ONBOOT="yes"
TYPE="Ethernet"
```

And same for local connection *ifcfg-eth1*

```
DEVICE="eth1"
BOOTPROTO="static"
IPADDR="10.1.36.1"
NETMASK="255.255.255.0"
NM_CONTROLLED="yes"
ONBOOT="yes"
TYPE="Ethernet"
```

Having networks working we shall be able to browse internet and install applications. Lets install `lshw` and add `HWADDR` to our configuration:

```
Yum -y install lshw
lshw -class network
```

Find serial numbers from networks with logical names that correlate to eth0 and eth1. Add `HWADDR` to network configurations like

```
HWADDR="0c:c4:7a:31:1b:20"
```

To both *`ifcfg-eth0`* and *`ifcfg-eth1`* respectively.

We shall configure `/etc/hosts.allow`

```
ALL: 10.1.36.0/24
ALL: 159.93.0.0/16
```

Now lets set up SSH server.

```
yum -y install openssh-server openssh-clients
chkconfig sshd on
service sshd start
```

And open tcp port 22. Edit `/etc/sysconfig/iptables` adding

```
-A INPUT -s 159.93.0.0/16 -p tcp -m state --state NEW -m tcp --dport 22 -j ACCEPT
-A INPUT -s 10.1.36.0/24 -p tcp -m state --state NEW -m tcp --dport 22 -j ACCEPT
```

And calling

```
service iptables restart
```

Now we can connect over SSH and be free from iKVM as default window to our server.

ZFS Configuration

For ZFS installation we will mainly follow this[9] instruction. We will be using SSH to perform all next operations.

Prepare Operating system

Lets update kernel and reboot

```
yum update kernel
yum -y install nano
yum install htop flex bison
```

Disable SELinux: edit `/etc/selinux/config`

```
SELINUX=disabled
```

And call

```
setenforce 0
```

Lets prepare tools

```
yum install -y git patch kernel-devel gcc zlib-devel libuuid-devel libtool automake autoconf
```

[9] https://rudd-o.com/linux-and-free-software/installing-fedora-on-top-of-zfs

and prepare development tools (following instructions for by Linux@CERN[10])

```
wget -O /etc/yum.repos.d/slc6-devtoolset.repo http://linuxsoft.cern.ch/cern/devtoolset/slc6-devtoolset.repo
yum install devtoolset-2
scl enable devtoolset-2 bash
```

Install OFED IB

InfiniBand Installation: get and unpack

```
wget https://openfabrics.org/downloads/OFED/ofed-3.18/OFED-3.18-rc3.tgz
```

Install packages

```
yum install libnl-devel libudev-devel libnl-devel
yum install tcl tk tcl-devel glib2-devel
```

Build and install Open Fabrics Enterprise Distribution (OFED) libraries

```
./install.pl --all --without-libfabric --without-libfabric-devel --without-libfabric-debuginfo --without-fabtests-debuginfo  --without-fabtests --without-libiwpm
```

At the end installation will output something like

```
Device (15b3:1003):
        81:00.0 Network controller: Mellanox Technologies MT27500 Family [ConnectX-3]
        Link Width: 8x
        PCI Link Speed: Unknown


Installation finished successfully.
```

Test

Install ZFS

```
sudo yum localinstall --nogpgcheck https://download.fedoraproject.org/pub/epel/6/x86_64/epel-release-6-8.noarch.rpm
sudo yum localinstall --nogpgcheck http://archive.zfsonlinux.org/epel/zfs-release.el6.noarch.rpm
sudo yum install -y kernel-devel zfs
sudo yum install spl
chkconfig zfs on
zpool status
```

We can now create ZFS Partitions.

```
zpool create -f zfs-data /dev/sdb
chmod 755 /zfs-data
zfs list
```

Yet our OS is installed on ext4! We would like to move it onto ZFS. Just moving files will not be enough – we need to make sure our boot loader supports our file system. GRUB 0.97 () is our default bootloader. It does not support ZFS, not developed any more and is considered Legacy. We want to update GRUB to version 2.

Download and build Grub 2.

Thus we shall download it from here[11] and compile using this instructions[12].

[10] http://linux.web.cern.ch/linux/devtoolset/#dts30
[11] http://www.gnu.org/software/grub/grub-download.html
[12] http://www.linuxfromscratch.org/lfs/view/development/chapter06/grub.html

```
cd /usr/src/spl-0.6.4.2/
./configure --prefix=/usr/src/build/
make -j24
make install
cd ../zfs-0.6.4.2/
./autogen.sh
./configure --with-spl=/usr/src/spl-0.6.4.2/ --prefix=/usr/src/build/
make -j24
make install
cd ../
git clone git://git.savannah.gnu.org/grub.git
cd grub/
./autogen.sh
./configure --prefix=/usr                       --sbindir=/sbin         --sysconfdir=/etc
--disable-grub-emu-usb            --disable-efiemu   --disable-werror --enable-libzfs  --with-
platform=efi LDFLAGS=-L/usr/src/build/lib/ CPPFLAGS=-I/usr/src/build/include/
make -j24
make install
```

Now we can check if zfs is supported

```
[root@localhost grub]# grub-probe  /zfs-data
zfs
```

Configure Grub 2

We will be mostly following GRUB2 Migration instructions[13] (note that `/boot` is installed on `/dev/sda1`)

```
[root@localhost src]# grub-install --grub-setup=/bin/true /dev/sda
Installing for i386-pc platform.
Installation finished. No error reported.
[root@localhost src]# grub-mkconfig -o /boot/grub/grub.cfg
Generating grub configuration file ...
Found linux image: /boot/vmlinuz-2.6.32-573.3.1.el6.x86_64
Found initrd image: /boot/initramfs-2.6.32-573.3.1.el6.x86_64.img
Found linux image: /boot/vmlinuz-2.6.32-504.el6.x86_64
Found initrd image: /boot/initramfs-2.6.32-504.el6.x86_64.img
done
```

Now we will try to chain load GRUB2 from legacy GRUB. We will edit `/boot/grub/grub.conf`

```
# grub.conf generated by anaconda
# Note that you do not have to rerun grub after making changes to this file
# NOTICE:  You have a /boot partition.  This means that
#          all kernel and initrd paths are relative to /boot/, eg.
#          root (hd0,0)
#          kernel /vmlinuz-version ro root=/dev/sdb3
#          initrd /initrd-[generic-]version.img
#boot=/dev/sdb1
default=0
timeout=30
splashimage=(hd0,0)/grub/splash.xpm.gz
```

[13] https://wiki.gentoo.org/wiki/GRUB2_Migration

```
# hiddenmenu

title GRUB2 Chainload
root (hd0,0)
kernel /grub/i386-pc/core.img
boot

title Scientific Linux (2.6.32-573.3.1.el6.x86_64)
root (hd0,0)
kernel /vmlinuz-2.6.32-573.3.1.el6.x86 64 ro root=UUID=2c6a38dc-04e7-41c3-ae85-623dbefa2b1e
rd_NO_LUKS rd_NO_LVM LANG=en_US.UTF-8 rd_NO_MD SYSFONT=latarcyrheb-sun16 crashkernel=auto
KEYBOARDTYPE=pc KEYTABLE=us rd_NO_DM rhgb quiet
initrd /initramfs-2.6.32-573.3.1.el6.x86_64.img

title anaconda bluesky (2.6.32-504.el6.x86_64)
root (hd0,0)
kernel /vmlinuz-2.6.32-504.el6.x86_64 ro root=UUID=2c6a38dc-04e7-41c3-ae85-623dbefa2b1e
rd_NO_LUKS rd_NO_LVM LANG=en_US.UTF-8 rd_NO_MD SYSFONT=latarcyrheb-sun16 crashkernel=auto
KEYBOARDTYPE=pc KEYTABLE=us rd_NO_DM rhgb quiet
initrd /initramfs-2.6.32-504.el6.x86_64.img
```

And after reboot we must see

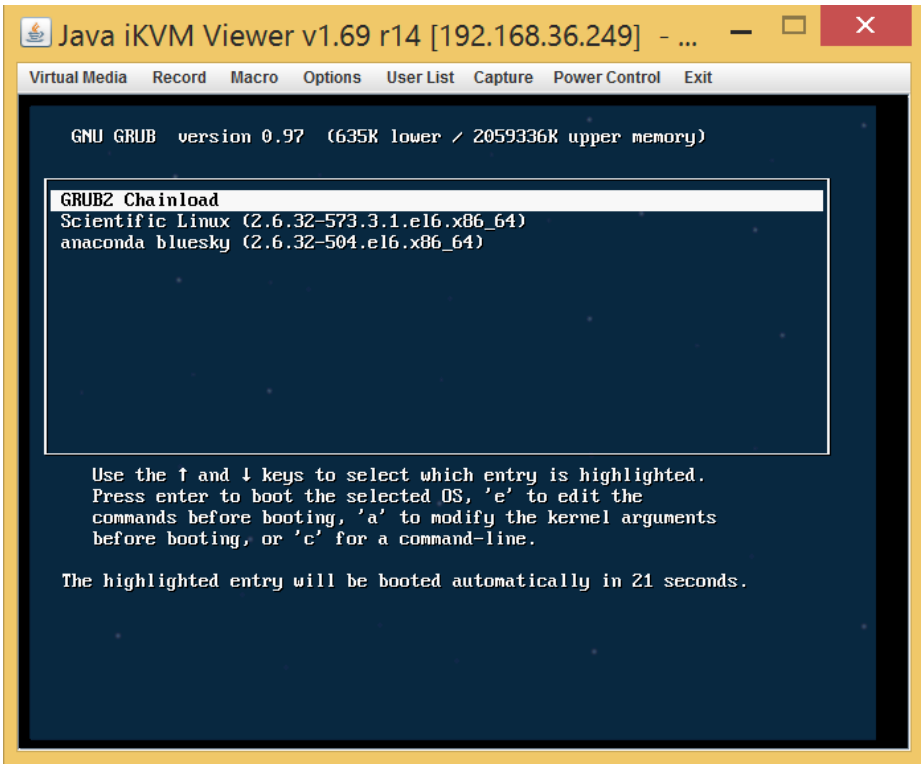

Figure 20: GRUB legacy chainloading GRUB2.

And GRUB2 shall chain load our OS.

Now we make GRUB2 default loader.

System launch on Blade

We used a network loading procedure developed at Hybrilit. It is based on traditional network load, modified for fast client OS updates, user work-process safety in case of server node failed.

Hybrilit administrators provided us with need files and instructions involving DHCP, SYSLINUX, TFTP, HTTP configurations, installation images for initd (called nanoramfs) and rootfs (called ramfs).

After services configuration we were able to chroot into image that would be unpaceked into blade memory and install/configure new software and drivers.

Note that for drivers' installation one must have same kernel versions on Server OS and on Blade OS.

Drivers Installation

We installed Mellanox OFED InfiniBand drivers and applications. (Similarly to host server installation)

We installed required packages:

```
yum install -y net-tools mc libnl-devel libudev-devel libnl-devel tcl tk tcl-devel glib2-devel
yum install -y git patch kernel-devel gcc zlib-devel libuuid-devel libtool automake autoconf
yum install redhat-rpm-config gcc-gfortran bison flex
yum install kernel-headers-2.6.32-573.3.1.el6.x86_64
yum install kernel-sources-2.6.32-573.3.1.el6.x86_64
ln -s /usr/src/kernels/2.6.32-573.3.1.el6.x86_64 /lib/modules/2.6.32-573.3.1.el6.x86_64/build
ln -s /usr/src/kernels/2.6.32-573.3.1.el6.x86_64 /lib/modules/2.6.32-573.3.1.el6.x86_64/source
```

Downloaded and unpacked files, created kernel specific drivers

```
wget http://www.mellanox.com/downloads/ofed/MLNX_OFED-3.0-2.0.1/MLNX_OFED_LINUX-3.0-2.0.1-rhel6.6-x86_64.tgz
./mlnx_add_kernel_support.sh  --mlnx_ofed /usr/src/MLNX_OFED_LINUX-3.0-2.0.1-rhel6.5-x86_64/
```

Unpacked them and installed:

```
./mlnxofedinstall -all
```

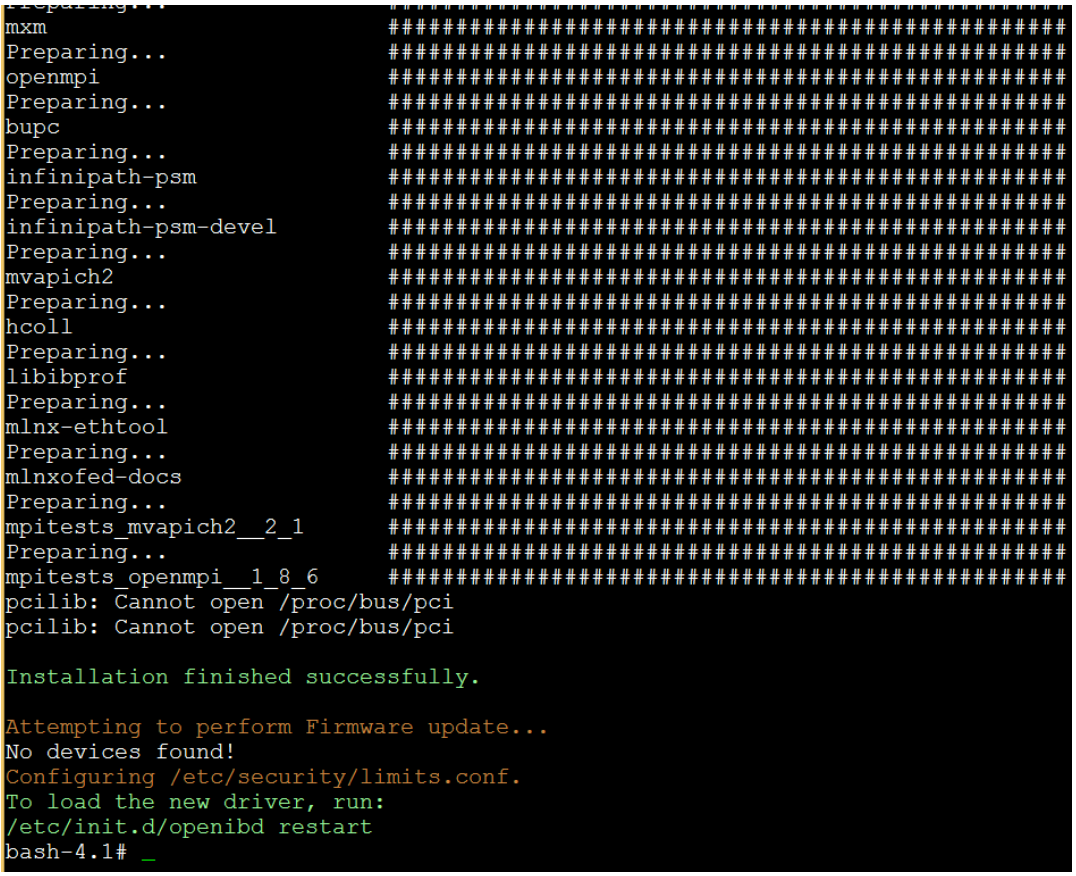

Figure 21: Mellanox OFED installation success.

IB problems we encountered during installation and testing

If compiled for one kernel and started on other drivers will fail:

```
ibpanic: [9765] main: can't init UMAD library: No such file or directory
-bash-4.1# service openibd start
Module mlx4_core belong to kernel which is not a part of ML[FAILED] skipping...
Module mlx4_ib belong to kernel which is not a part of MLNX[FAILED]kipping...
Module mlx4_en belong to kernel which is not a part of MLNX[FAILED]kipping...
Module mlx5_core belong to kernel which is not a part of ML[FAILED] skipping...
Module mlx5_ib belong to kernel which is not a part of MLNX[FAILED]kipping...
Module ib_umad belong to kernel which is not a part of MLNX[FAILED]kipping...
Module ib_uverbs belong to kernel which is not a part of ML[FAILED] skipping...
Module ib_ipoib belong to kernel which is not a part of MLN[FAILED]skipping...
Loading HCA driver and Access Layer:                       [  OK  ]
Module rdma_cm belong to kernel which is not a part of MLNX[FAILED]kipping...
Module ib_ucm belong to kernel which is not a part of MLNX_[FAILED]ipping...
Module rdma_ucm belong to kernel which is not a part of MLN[FAILED]skipping...
udev: starting version 147
udevstart: No devices created under /dev/infiniband        [WARNING]
-bash-4.1# ibv_devinfo
Failed to get IB devices list: Function not implemented
-bash-4.1# ibstat
ibwarn: [10633] umad_init: can't read ABI version from /sys/class/infiniband_mad
/abi_version (No such file or directory): is ib_umad module loaded?
ibpanic: [10633] main: can't init UMAD library: No such file or directory
-bash-4.1# ibstatus
Fatal error:  device '*': sys files not found (/sys/class/infiniband/*/ports)
-bash-4.1#
```

Figure 22Kernels mismatch.

We have seen an interesting error when driver was recompiled on Blade

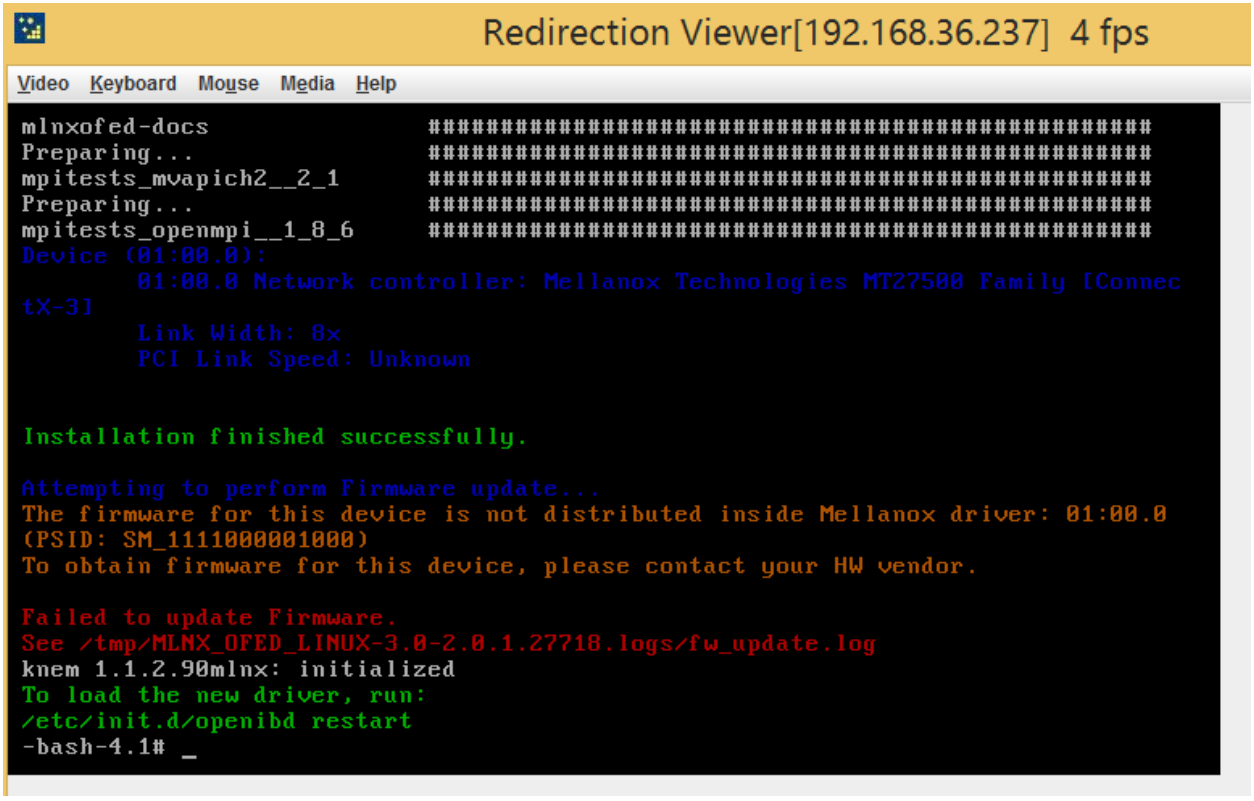

Figure 23: Problems with on Blade Mellanox OFED drivers recompilation.

InfiniBand testing

We installed IB on two baldes, devices were found yet links were in DOWN state:

```
mlx4_core 0000:01:00.0: mlx4_ib_add: allocated counter index 1 for port 1
mlx4_en: Mellanox ConnectX HCA Ethernet driver v3.0-2.0.0 (13 Jul 2015)
mlx4_en 0000:01:00.0: registered PHC clock
card: mlx4_0, QP: 0x220, inline size: 120
Default coalesing params for mtu:4092 - rx_frames:88 rx_usecs:16
Loading HCA driver and Access Layer:                       [  OK  ]
-bash-4.1# ibstat
CA 'mlx4_0'
        CA type: MT4099
        Number of ports: 1
        Firmware version: 2.11.500
        Hardware version: 0
        Node GUID: 0x002590ffff908680
        System image GUID: 0x002590ffff908683
        Port 1:
                State: Down
                Physical state: Polling
                Rate: 10
                Base lid: 0
                LMC: 0
                SM lid: 0
                Capability mask: 0x02514868
                Port GUID: 0x002590ffff908681
                Link layer: InfiniBand
-bash-4.1# _
```

Figure 24: ibstat call.

Redirection Viewer[192.168.36.237] 4 fps

Video Keyboard Mouse Media Help

```
                SM lid: 0
                Capability mask: 0x02514868
                Port GUID: 0x002590ffff908681
                Link layer: InfiniBand
-bash-4.1# ibv_devinfo
hca_id: mlx4_0
        transport:                      InfiniBand (0)
        fw_ver:                         2.11.500
        node_guid:                      0025:90ff:ff90:8680
        sys_image_guid:                 0025:90ff:ff90:8683
        vendor_id:                      0x02c9
        vendor_part_id:                 4099
        hw_ver:                         0x0
        board_id:                       SM_1111000001000
        phys_port_cnt:                  1
                port:   1
                        state:                  PORT_DOWN (1)
                        max_mtu:                4096 (5)
                        active_mtu:             4096 (5)
                        sm_lid:                 0
                        port_lid:               0
                        port_lmc:               0x00
                        link_layer:             InfiniBand

-bash-4.1# _
```

Figure 25: ibv_devinfo call.

```
-bash-4.1# ibstatus
Infiniband device 'mlx4_0' port 1 status:
        default gid:     fe80:0000:0000:0000:0025:90ff:ff90:8681
        base lid:        0x0
        sm lid:          0x0
        state:           1: DOWN
        phys state:      2: Polling
        rate:            10 Gb/sec (4X)
        link_layer:      InfiniBand

-bash-4.1# _
```

Figure 26: ibstatus call.

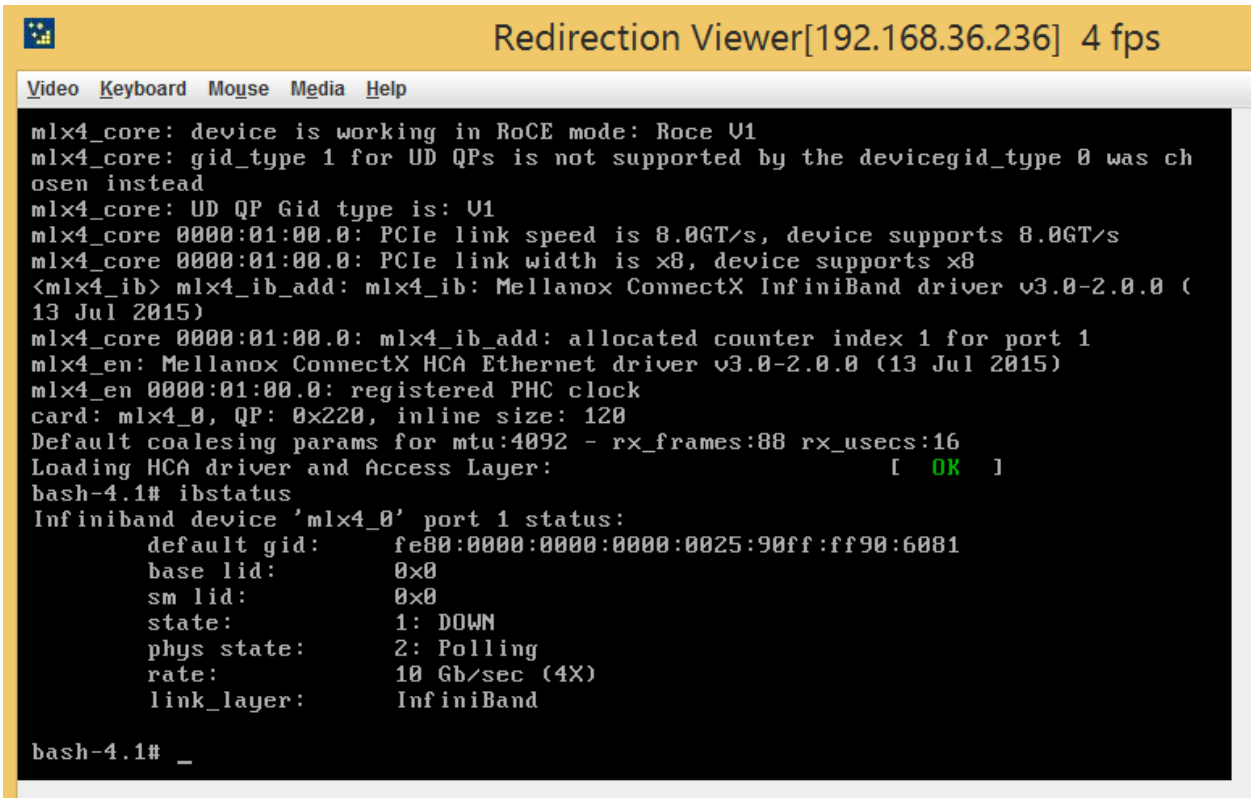

Figure 27ibstatus call on another node.

We tried ping-pong nodes over IB yet attempt failed with nodes not seeing one another.

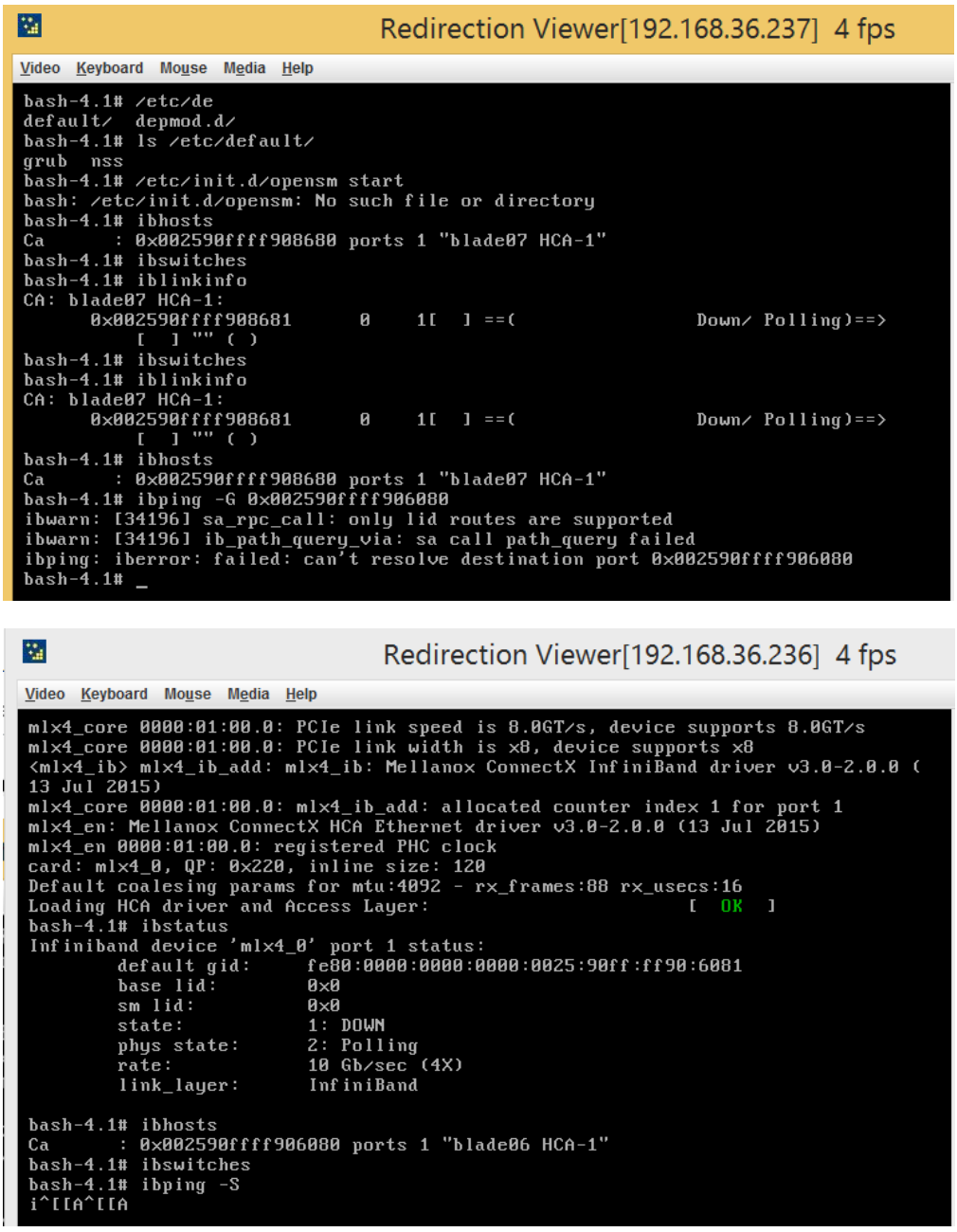

Figure 28: ibping failed.

Conclusion

During period of summer program, we explored technologies that were new for me such as: IPMI, MegaPCLI RAID, ZFS, installation of a system on a disc less system. InfiniBand was not configured during given time period, yet attempts were made and we accomplished some progress.

A presentation of the obtained results was given at a public LIT JINR seminar. It was accepted well and spawned a productive discussion.

We hope to continue our work remotely for further exploration of cluster technologies.